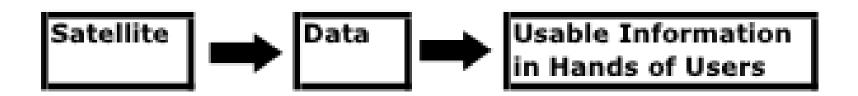
## **ASTROTROP**



**Alan Grainger**University of Leeds

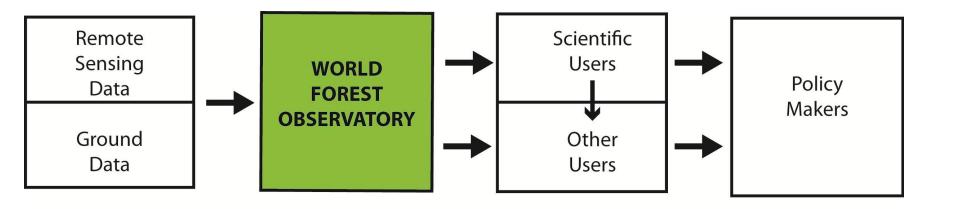




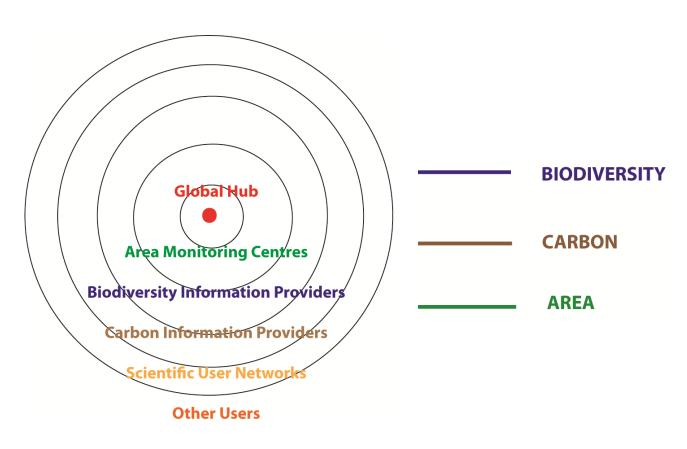
# World Forest Observatory Proposals 2010-11



# A Scientific Community Collaborating to Use a New Global Instrument



## **World Forest Observatory Structure**







## **Roles and Partners**

Role	Partners
Regional monitoring centres	Columbia U, U Jena, Keio U, Peking U, S Dakota State U, VTT, Woods Hole RC, Conabio
Carbon	Woods Hole RC, IIASA, Carnegie I
Biodiversity	UNEP WCMC, Smithsonian
Global hub & synthesis	U Leeds, Smithsonian
In situ	Smithsonian, U Leeds
Networking	U Helsinki, IIASA
Validation	Columbia U, Wageningen U
Verification	Resources for Future, IIASA, Wageningen

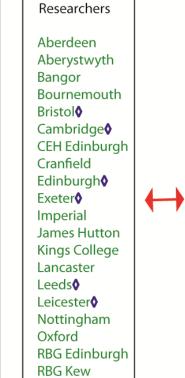
# ASTROTROP PROJECT 2013-16

#### ASTROGRID/ EURO-VO

Bristol
Cambridge
Edinburgh
Exeter
Glasgow
Heidelberg
Leicester
Leeds
Manchester
NAI Trieste
RAL

Strasbourg

UCL



Sheffield Surrey

UCL**◊** York

Other

Scientific

**Networks** 

Companies

Delta T

DMCII

**RCUK** 

NCFO

**CFDA** 

UKATC

Daresbury

Stakeholders

Ecometrica

Forestry Com

Global Canopy

**TROPGLOBE** 

Other

Stakeholders

**DEFRA** 

ISIC

# **ASTROTROP Partners**

#### **Information Inputs**

Area Maps from Kings College (L. America) Leicester (Congo)

Maps of Other Attributes from Other Partners

## STFC Funded Technology

#### **Technology Users**

Scientific

Users

Information





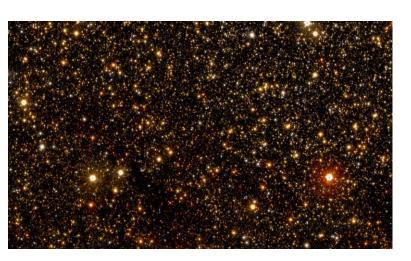
1.8 billion hectares 400 billion trees

Attributes: area, location, carbon density, species

**Functions: combine information from 100s of sources** 

overlay information on different attributes

# Managing Tropical Forest Information and Astronomical Data



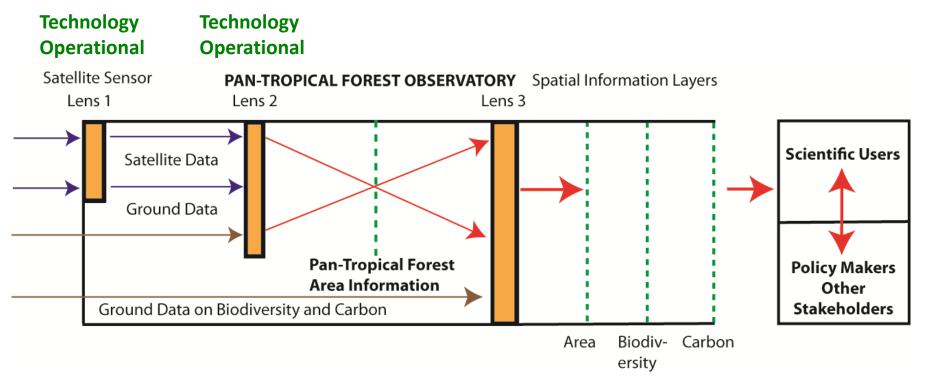
200 billion stars in the Milky Way

**Attributes: location** 

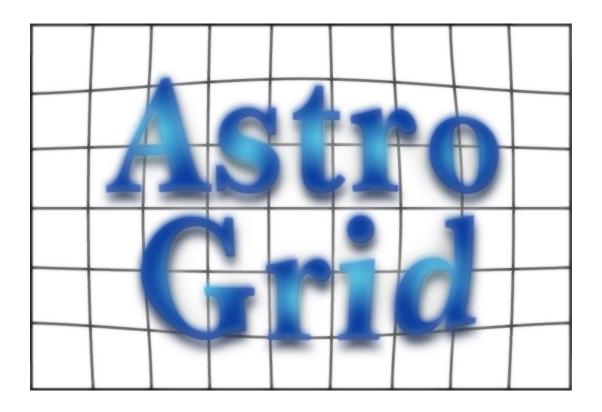
Functions: combine information from 100s of sources

overlay information on different attributes

### **How a Pan-Tropical Forest Observatory Will Work**



The Third Lens: Virtual Superimposition



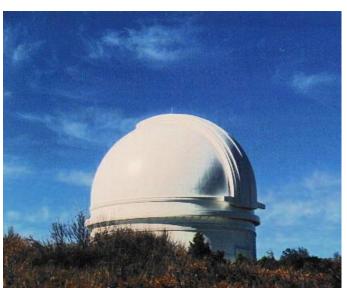
#### Web

All docs in the world inside your PC

### Virtual Observatory

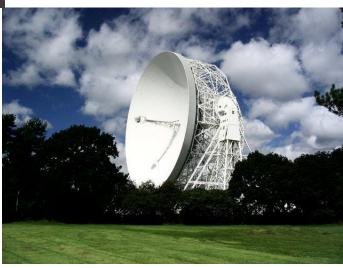
All databases in the world inside your PC





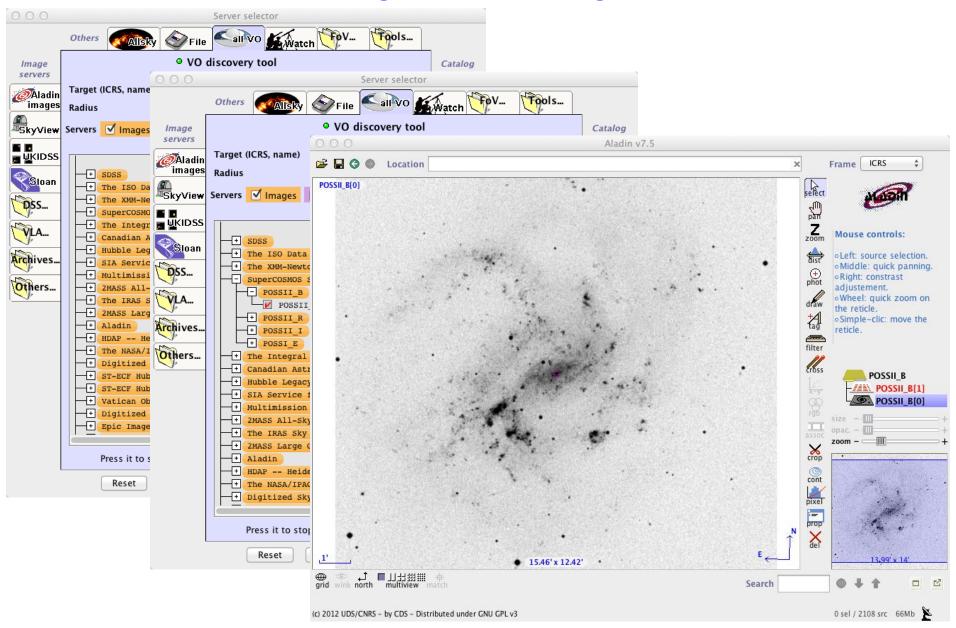






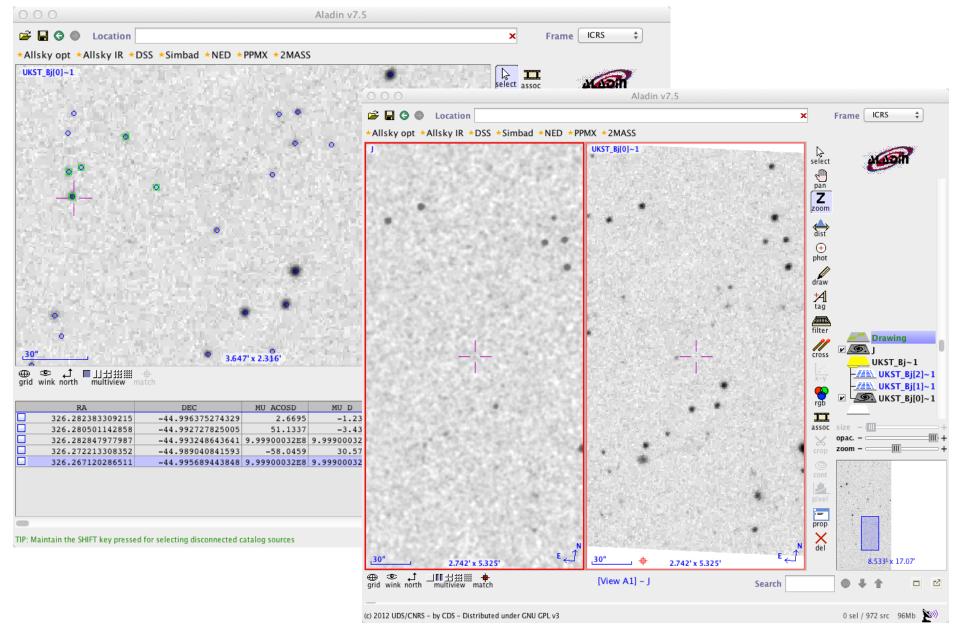
## **VO** in action

#### searching the VO for image data



### **VO** in action

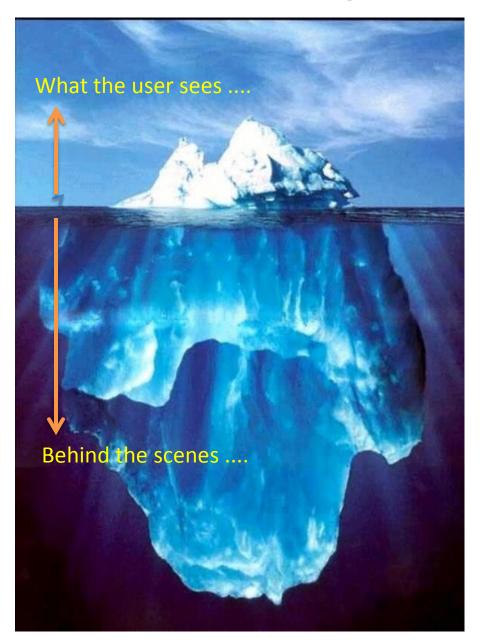
#### **Grab, Overlay and Compare Images**

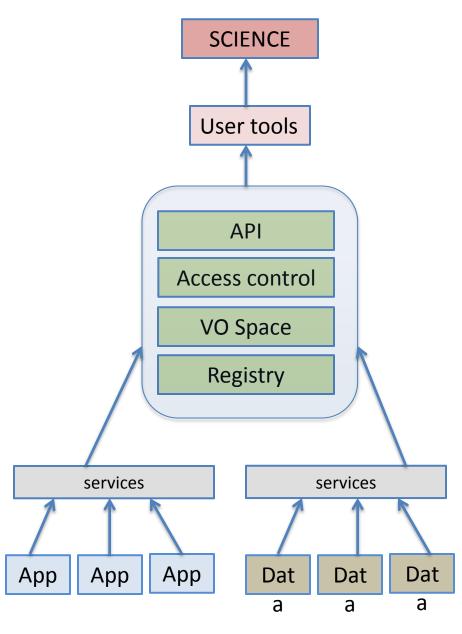


## Parts of a VO

- All databases listed in Registries, or 'Yellow Pages'
- Databases selected via their Metadata
- Data grabbed from selected database using Grabbing Services
- Data analysed using Manipulation Tools
- Depends on:
  - Agreed standards
  - Services and applications which understand VO rules
  - Middleware which glues everything together

## The iceberg





## **Prototype ASTROTROP Software**

	Astrogrid	ASTROTROP
Data models	Obscore	Worldfile GIS metadata
Standards bodies (Existing)	IVOA	Open Geospatial Consortium
Registries	Registry	CKAN – Comprehensive Knowledge Archive Network Or GEONODES
Data Grabbing Services	SIAP	Geoserver
Data Manipulation Tools	Aladin	QGIS

## **Applications**

#### Virtual World Forest Observatory in which:

- Users all over the world access multiple attribute data and multi-sensor data (e.g. Landsat, LIDAR etc.)
- BUT data stay in their host databases
- Local people can validate maps

#### Combine Spatially Decentralized Databases

- National forest inventories by provinces in large countries
- Citizen observatories in hundreds of towns etc.

#### Combine Multiple Databases in Large Groups

- International research projects
- Research councils
- Mapping organizations

## **Next Steps**

 Demonstrate prototype virtual observatory at February Conference

- Agree on initial standards at Conference
  - Metadata
  - Table formats

Establish Working Group to agree on further standards over time

## **IVOA Standards Working Groups**

Working Group	Standards for
Applications	Rules for data manipulation tools
Data Model	Metadata list format
Data Access Layer	Table Access Protocol, Search, Grab
Registries	Formats for registry listings
Grid and Web Services	Using VO Space
Semantics	Terms and ontologies